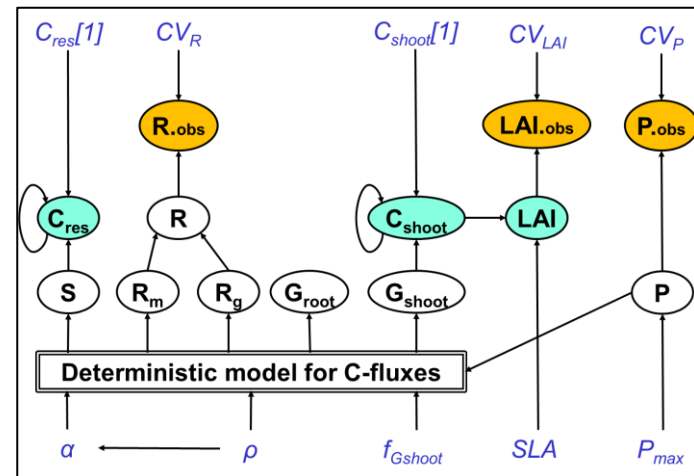
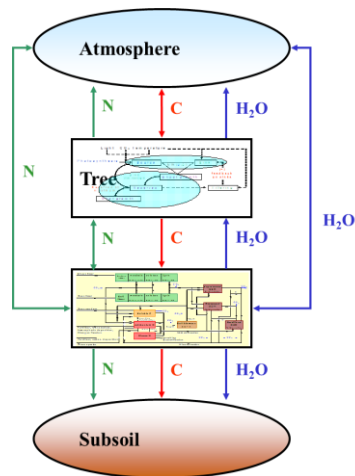


Bayesian Methods for Ecological and Environmental Modelling: COMMUNICATION



Marcel van Oijen, Lindsay Banin, David Cameron, Peter Levy, Kate Searle

CEH-Edinburgh, 2019-09-12

Contents

- 1. Introduction**
- 2. Co-design & graphical modelling**
- 3. Reporting results**
- 4. Visualisation of uncertainty**
- 5. Discussion**

1. Introduction

1.1 Purpose , ToWhom-What-How, Guidelines?

- **What is the purpose of the communication?**
- **Are you co-designing a model, or is the study finished and are you reporting results?**
 - Graphical modelling is very good for the first purpose, less so for the second
 - Reporting results: *To whom? What? How?*
- **Are there guidelines for visualising uncertainty?**

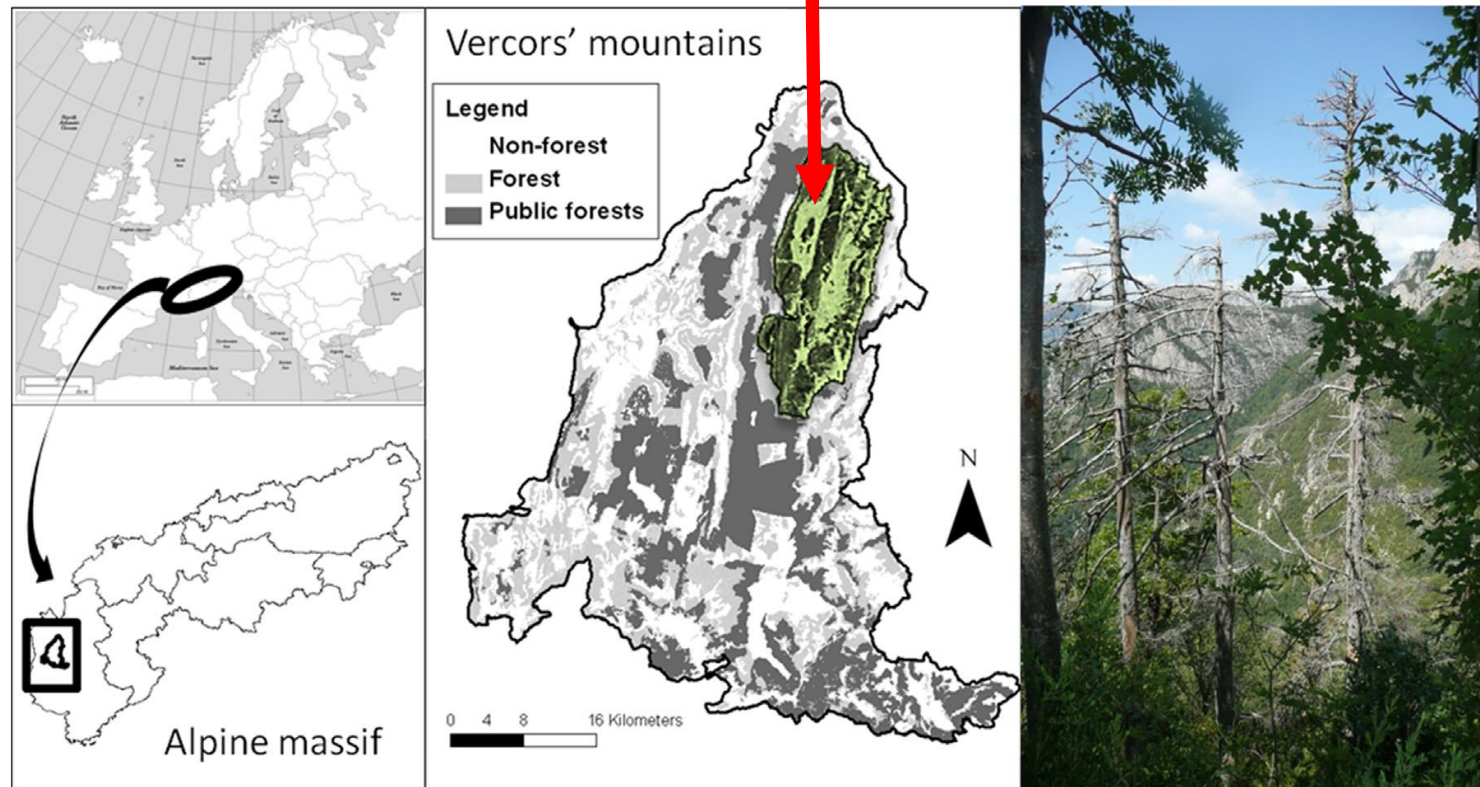
2. Co-design & graphical modelling

2.1 Decision-support

How to make LS-modelling useful for decision-making?

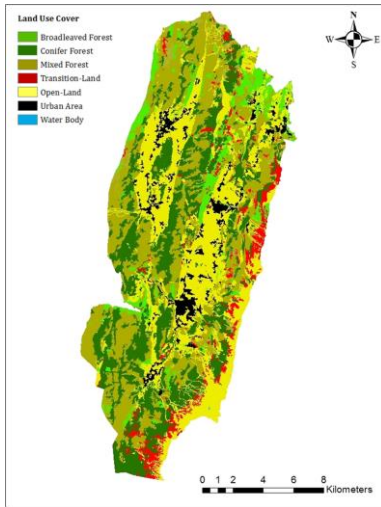
- *Stimulate involvement of stakeholders*
- *Recognise uncertainties*

Production or conservation?

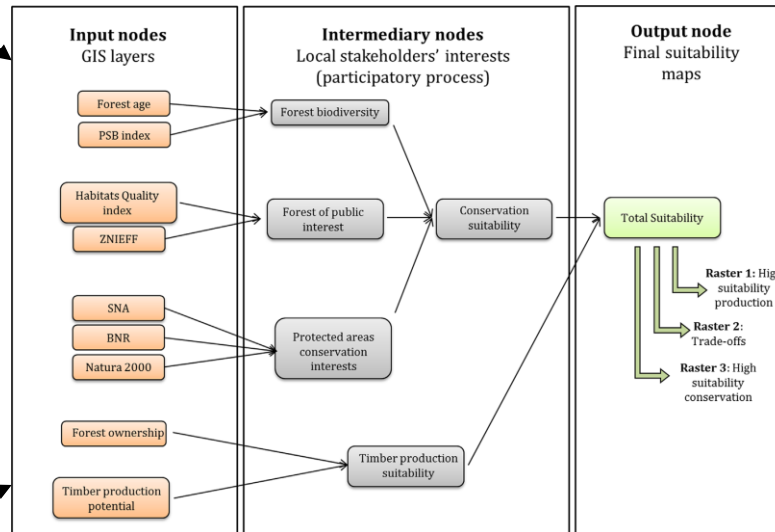


2.2 Production or conservation? GIS + BBN

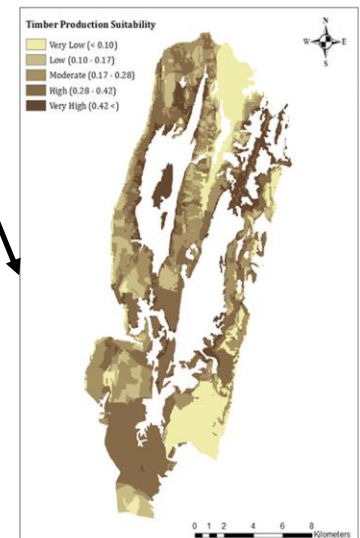
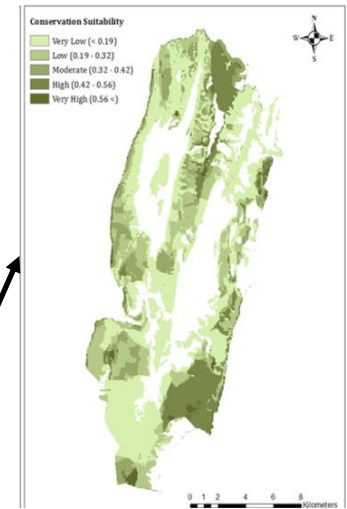
GIS: inputs



BBN: conditional probabilities

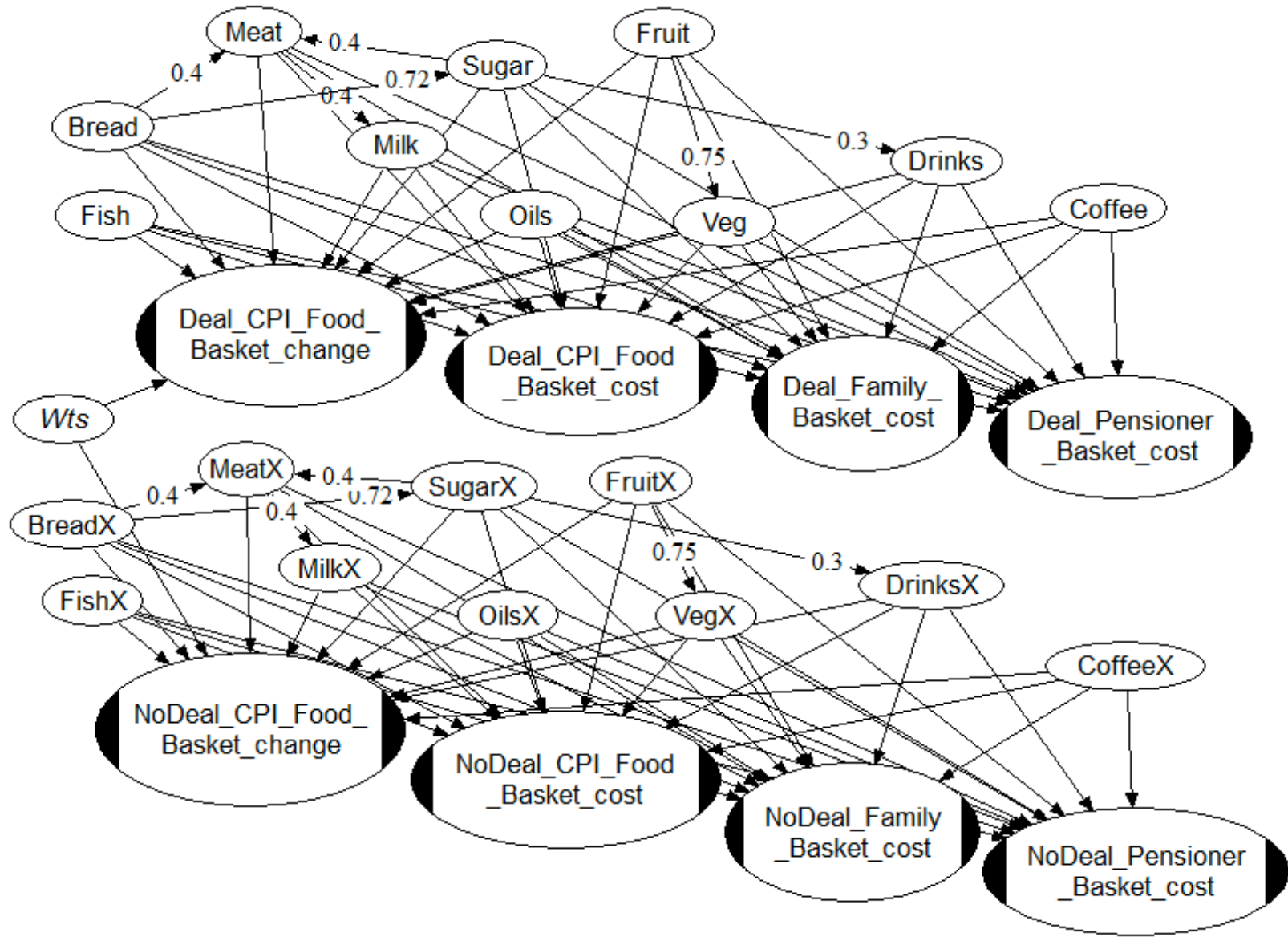


GIS: outputs



Gonzales-Redin et al. (2016)

Impacts of Brexit scenarios on UK food prices using structured expert judgement



3. Reporting results

3.1 Reporting: To whom? What? How

– Reporting to whom?

- Colleagues or stakeholders? Listeners, readers (posters or papers), or app-users?

– What?

- Main message: methodological <-> application?
- Checklist: Reporting prior, likelihood, algorithm, software, quality test of MCMC, posterior parameter uncertainty, posterior predictive uncertainty
 - *E.g.: beta priors, Gaussian likelihoods for residuals from PBM, Metropolis, BayesianTools, Gelman-Rubin < 1.01, Posterior histograms parameters, Posterior prediction bands for output variables*

– How?

- Text, tables, figures, interactive app

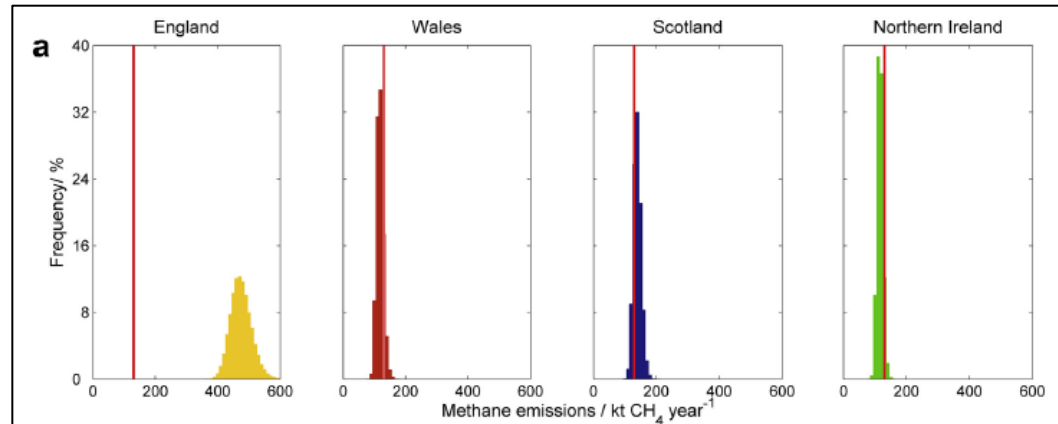
4. Visualisation of uncertainty: Guidelines

Milne et al. (2015): Communicating the uncertainty in GHG emissions

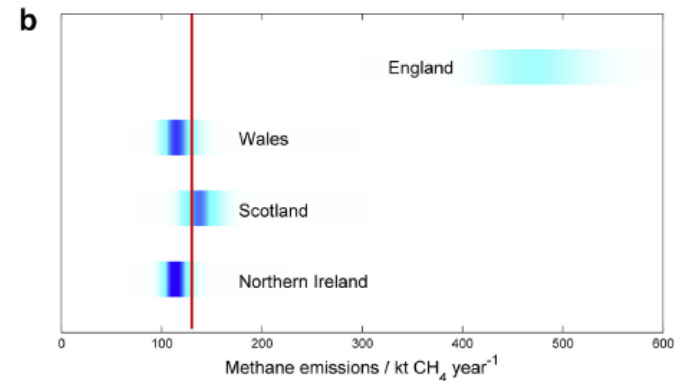
Communicating the uncertainty in estimated greenhouse gas emissions from agriculture

Alice E. Milne ^{a,*}, Margaret J. Glendining ^a, R. Murray Lark ^b, Sarah A.M. Perryman Taylor Gordon ^a, Andrew P. Whitmore ^a *Journal of Environmental Management* 160 (2015) 139–153

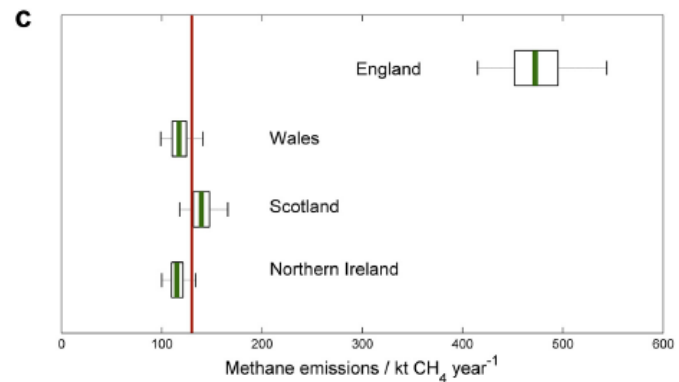
Histograms



Shaded arrays

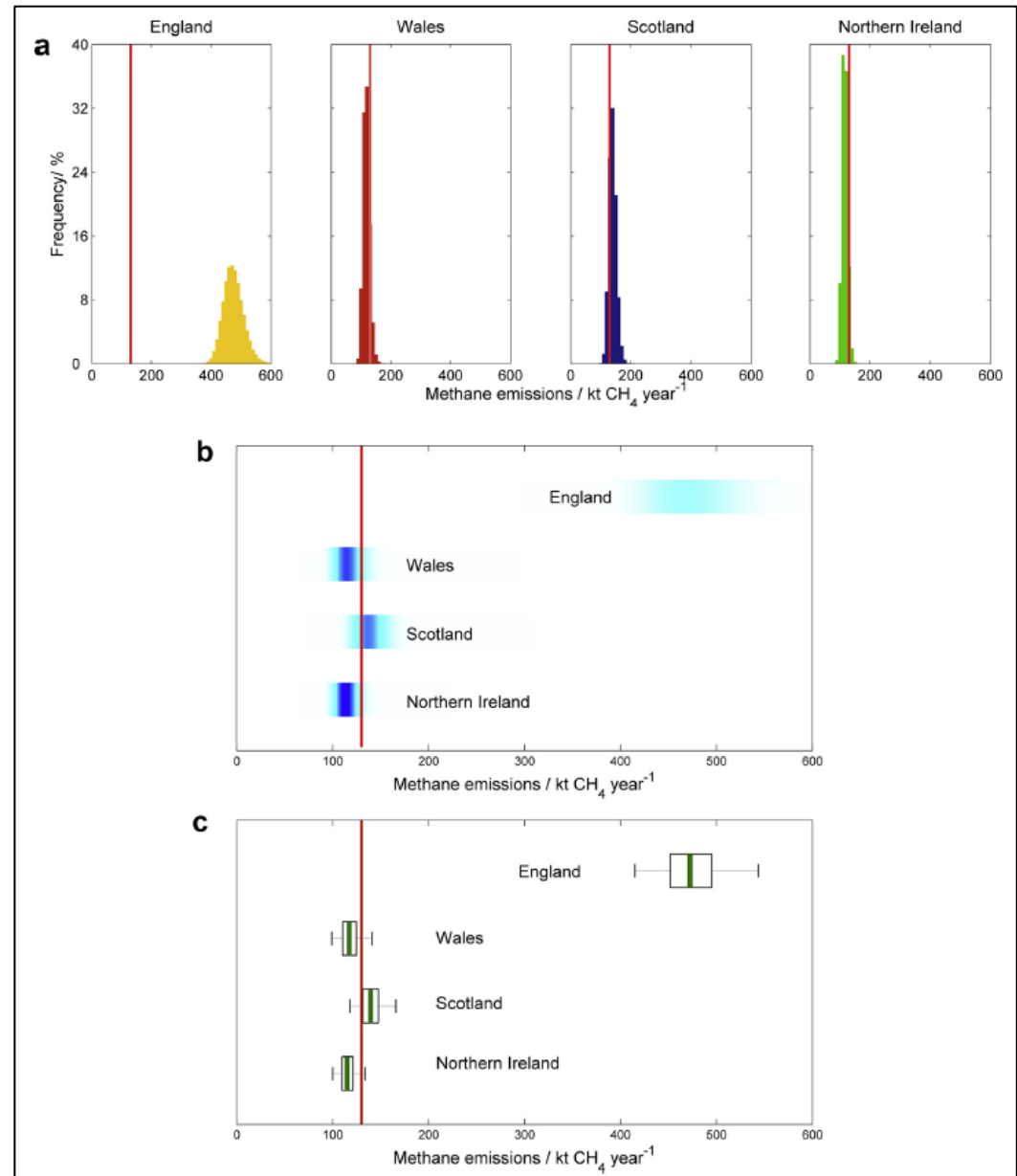


Boxplots



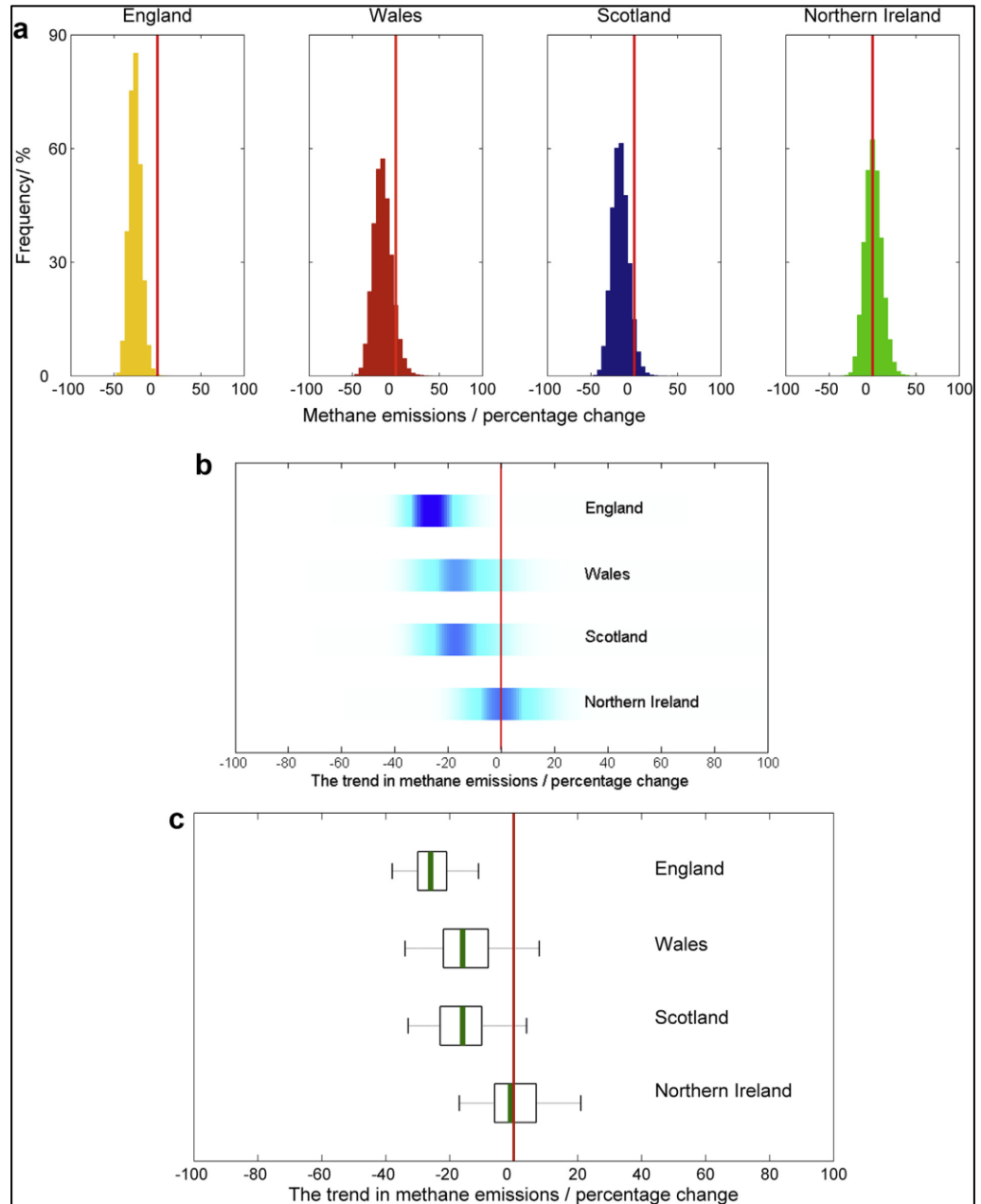
Milne et al. (2015): Communicating the uncertainty in GHG emissions

■ Is it clear that the estimated emissions are most uncertain for England?

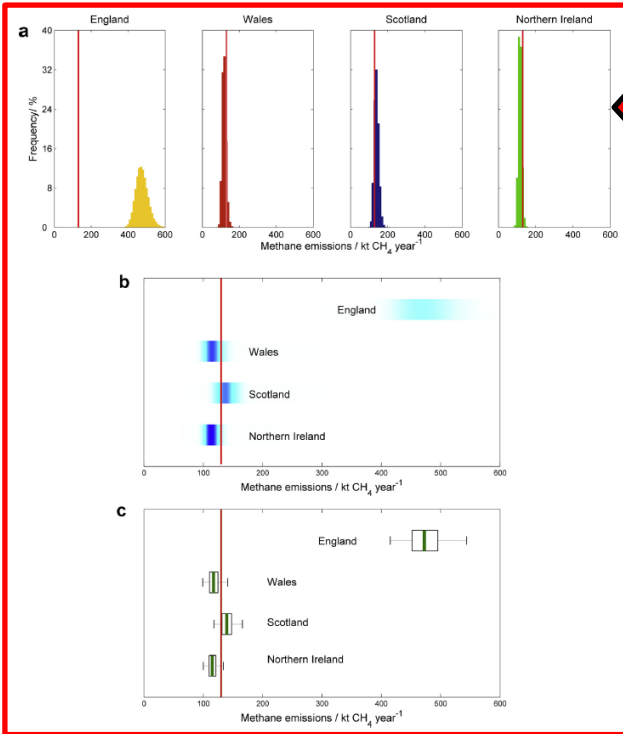


Milne et al. (2015): Communicating the uncertainty in GHG emissions

■ It is more uncertain that emissions from Scotland have reduced than that emissions from England have reduced?

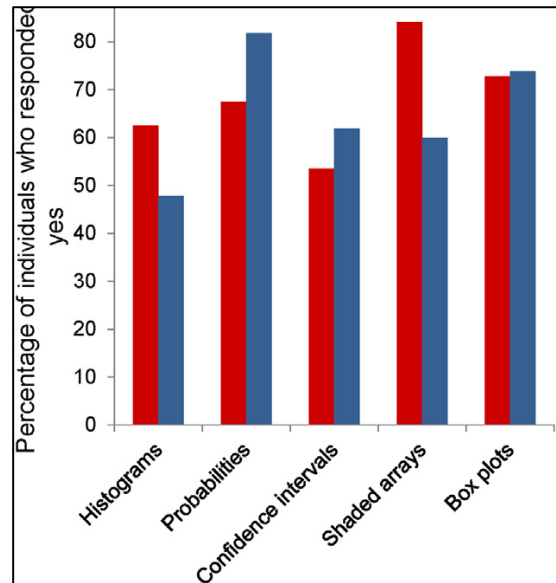
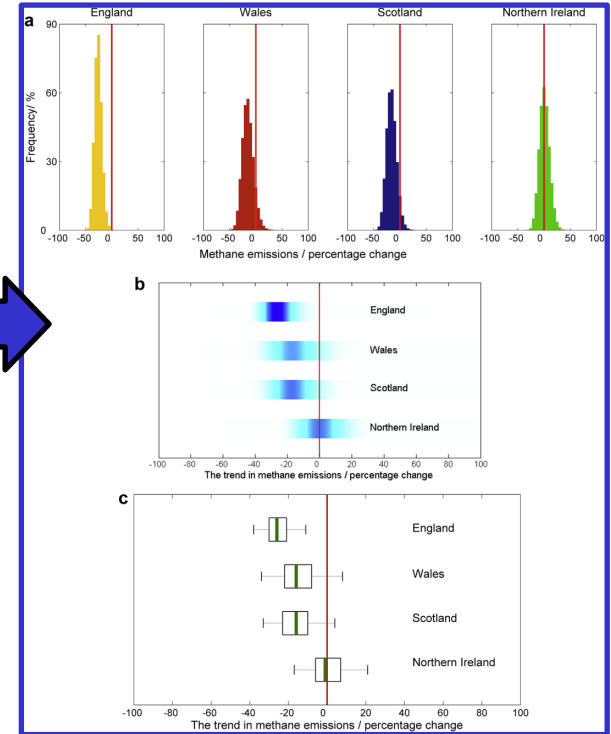


Milne et al. (2015): Communicating the uncertainty in GHG emissions



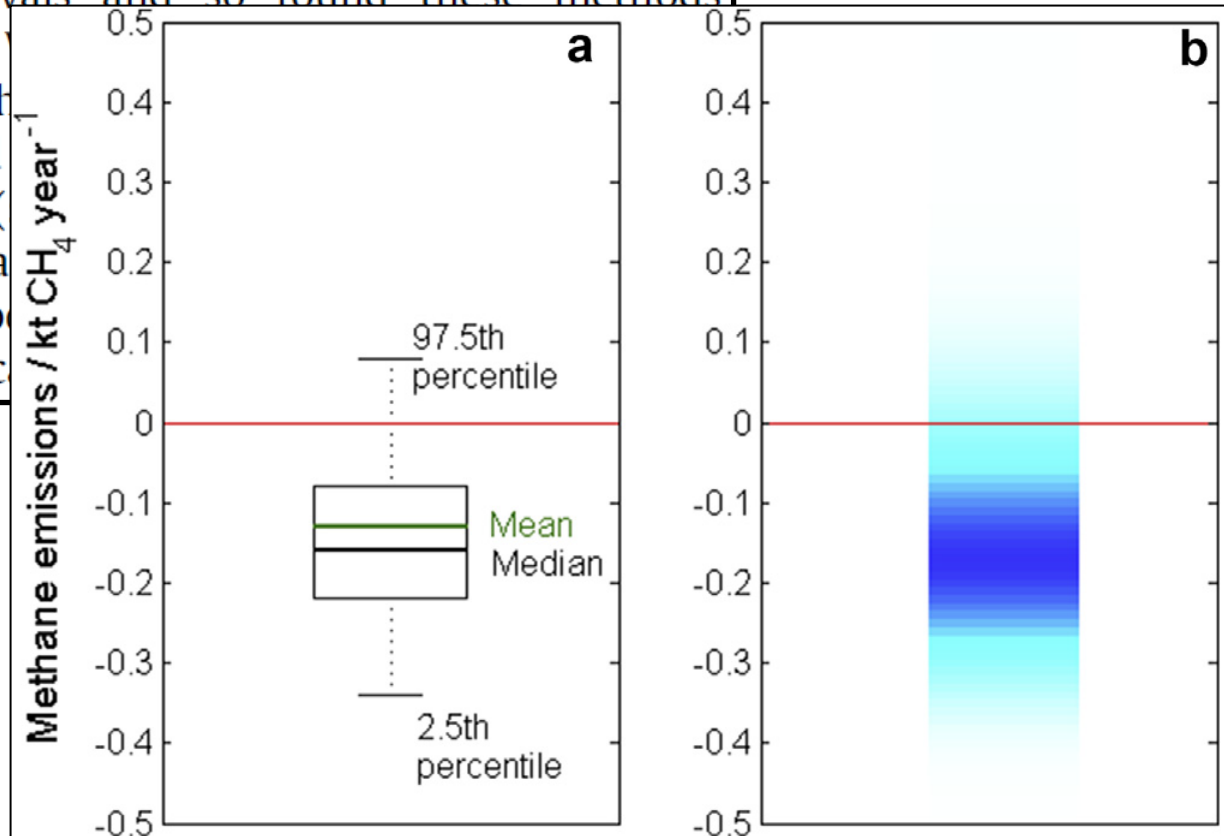
■ Is it clear that the estimated emissions are most uncertain for England?

■ It is more uncertain that emissions from Scotland have reduced than that emissions from England have reduced?



5. Conclusion and recommendation

The methods chosen to communicate uncertainty in estimates of greenhouse gas emissions should be influenced by professional and mathematical background of the target audience. In our study we found that research scientists tended to be familiar with box-plots and confidence intervals and so found these methods straightforward to interpret. with summary statistics such as percentiles provide a sound combination of intuitive methods with shaded arrays with numeric



PRINCIPLES OF POSTERIOR VISUALIZATION (2015)

Blog by Mikhail Shubin:

<https://ctg2pi.wordpress.com/2015/02/24/principles-of-posterior-visualization/>

A) Gamma distribution

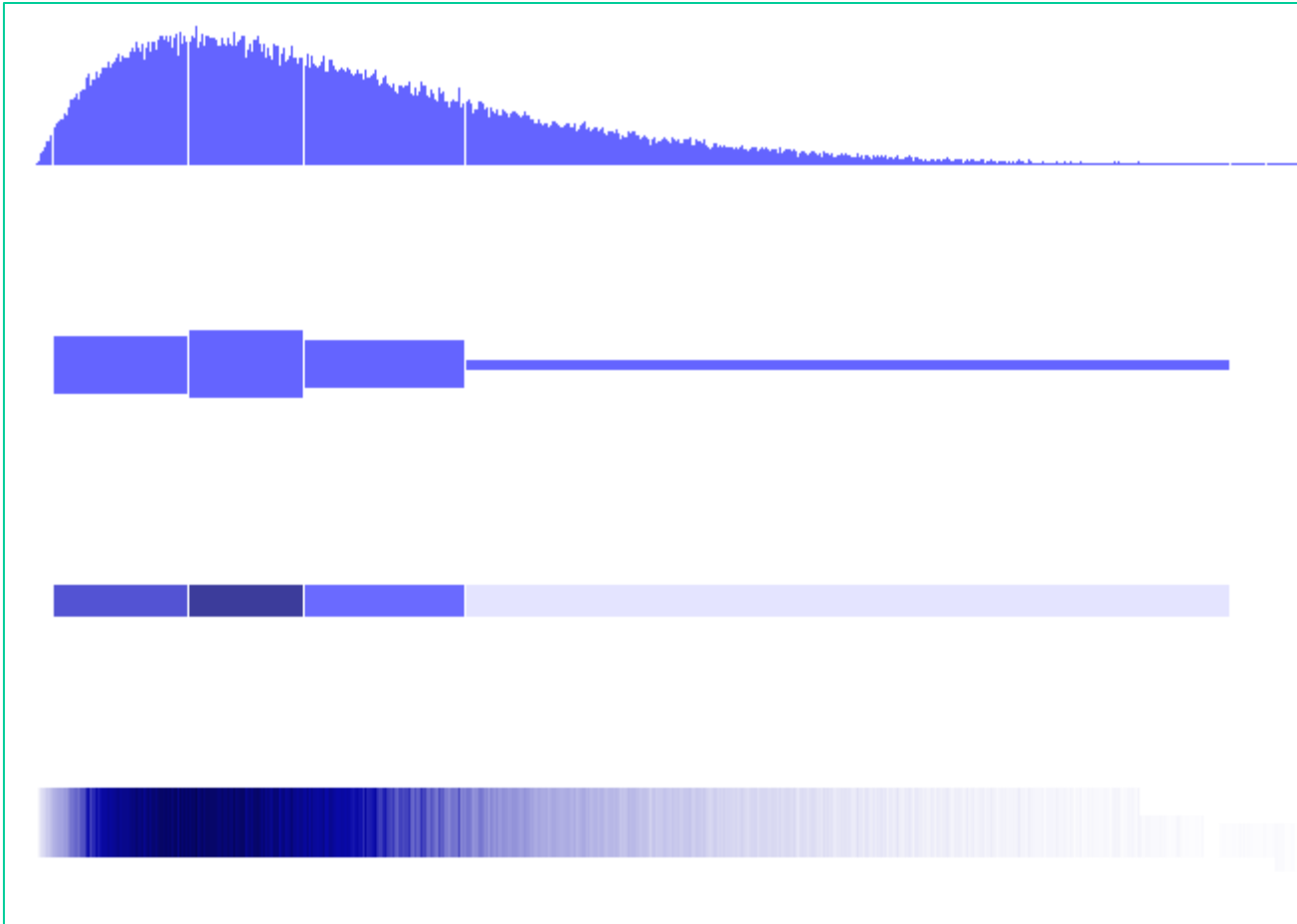


B) Corresponding boxplot.



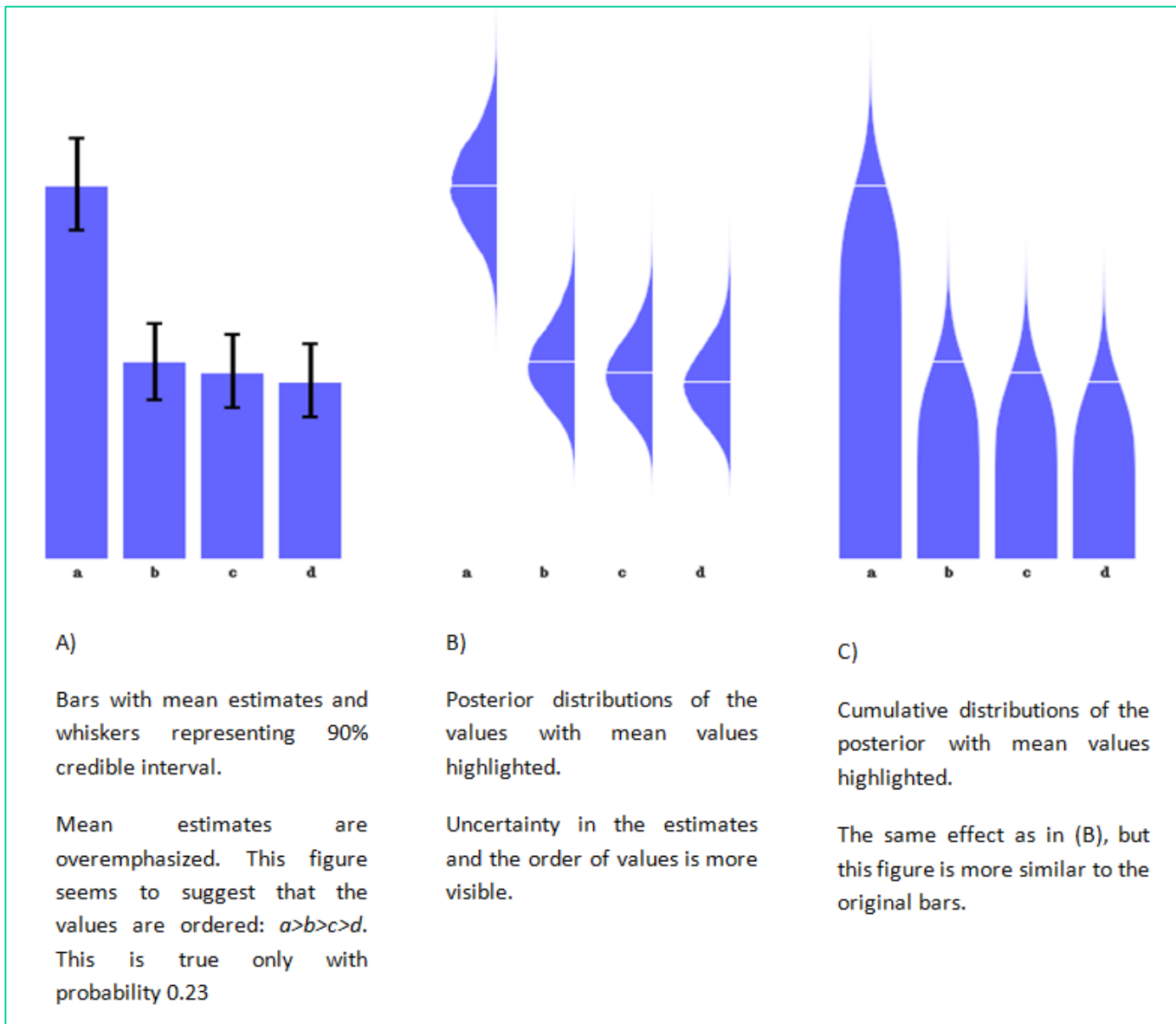
This and this intervals have almost the same probability to contain the true value (24.5% vs. 25%). However, the second interval looks much bigger. Boxplot is misleading

Principle: Equal probability = Equal ink

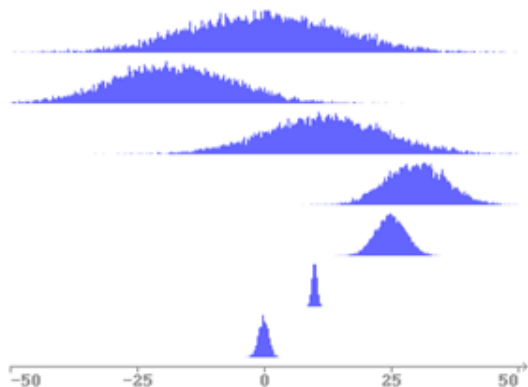


PRINCIPLES OF POSTERIOR VISUALIZATION (2015)

Principle: Do not overemphasize the point estimate



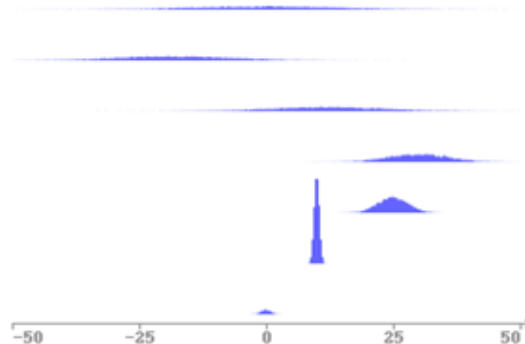
PRINCIPLES OF POSTERIOR VISUALIZATION (2015)



A)

All histograms have the same height.

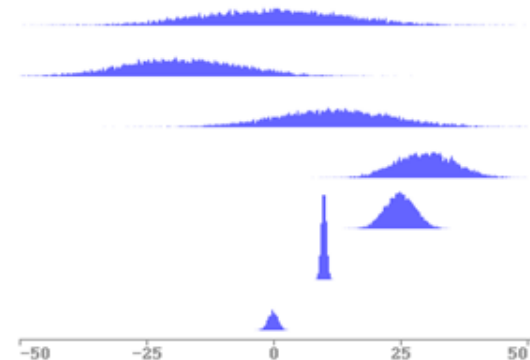
Histograms of the most uncertain estimates dominate the visual space.



B)

Y-axes of all histograms have the same scale.

Histograms of the uncertain estimates are barely readable.



C)

The height of each histogram is proportional to the square root of its height as on Panel B.

Precise estimates are highlighted while uncertain estimates remain readable.

Kleineberg et al. (2019): Visualizing Uncertainty

Preliminary Version
March 2019

A Catalogue of VISUALISATIONS

11-STEP STRATEGY for UNCERTAINTY VISUALIZATION DESIGN

1. IDENTIFY
the UNCERTAINTY
visualisation task

2. UNDERSTAND
the DATA that is
to be visualised

3. UNDERSTAND WHY
WHY uncertainty needs to be visualised
and how it needs to help the user

4. DECIDE
which uncertainty should be visualized

5. DECIDE
on a definition of uncertainty

6. DETERMINE
the specific causes of the uncertainty

7. DETERMINE
the causal categories of the uncertainty

8. DETERMINE
the visualisation requirements

9. PREPARE
uncertainty for
visualisation

10. TRY
different
techniques

11. FEEDBACK
Get audience opinions and criticisms

figure 2: The stepwise process for visualisation of uncertainty

A PUBLICATION OF THE
ANALYSIS UNDER UNCERTAINTY for
DECISION MAKERS NETWORK

Kleineberg et al. (2019): Visualizing Uncertainty

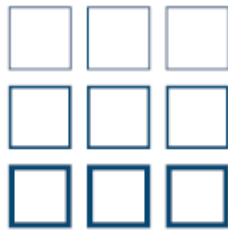
ATTRIBUTES of GRAPHICS



SHAPE



ENCLOSURE



LINE WIDTH



SATURATION



COLOUR HUE



VALUE



SIZE



TEXTURE



ORIENTATION



POSITION



3D



JUXTAPOSITION



LENGTH



CURVATURE



DENSITY



CLOSURE



SHARPNESS



TRANSPARENCY

Kleineberg et al. (2019): Visualizing Uncertainty

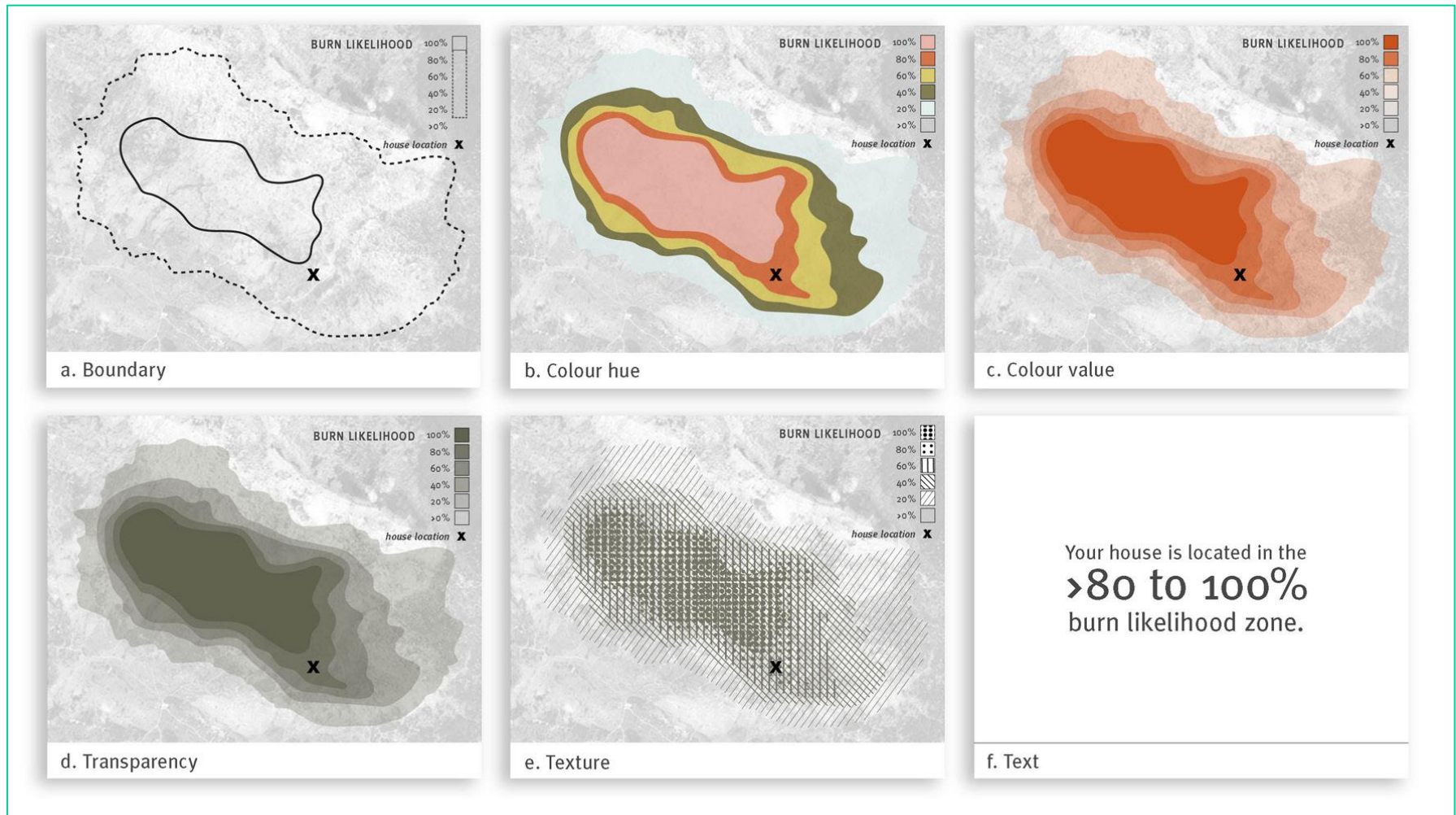


figure 8: Comparing changing different attributes to communicate uncertainty, research shows that representations involving hue(b), value(c) and transparency(d) work best.

Kleineberg et al. (2019): Visualizing Uncertainty

Bar chart with error bars

length of bar = proportional to the values they represent.
whiskers represent error margin (here ± 5)

Resources

General Background:

How do you c

Nesta Sparks lec

<https://www.you>

Visualising th

<https://flowingd>

Visualising co

<https://www.acl>

Design

Free images:

<https://pixabay.c>

<https://unsplash>

<https://thenoun>

Catalogue of

<http://www.reth>

<https://datavizca>

Tutorials

<https://flowingd>

Platforms for Data Visualisations

Microsoft

<https://powerbi.microsoft.com/en-us/>

R shiny

<https://shiny.rstudio.com/gallery/>

Tableau

<https://www.tableau.com/>

D3

<https://github.com/d3/d3/wiki/Gallery>

figure 13: C

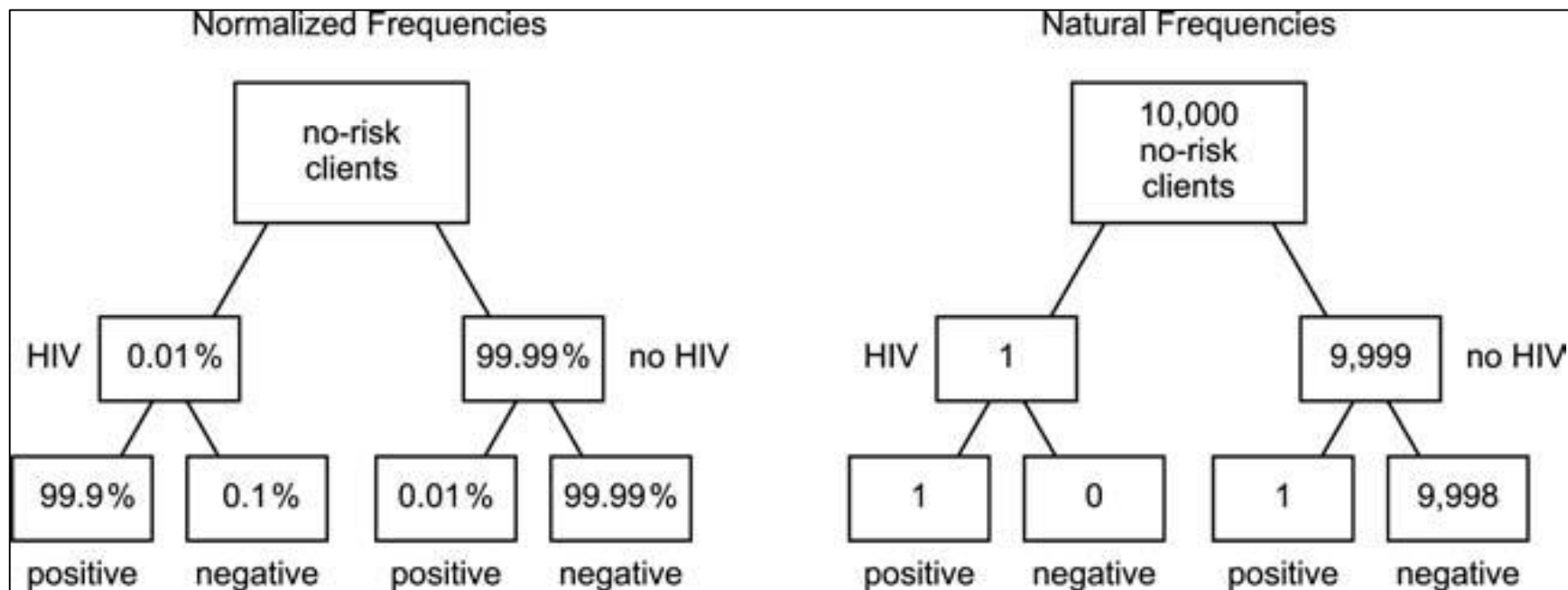
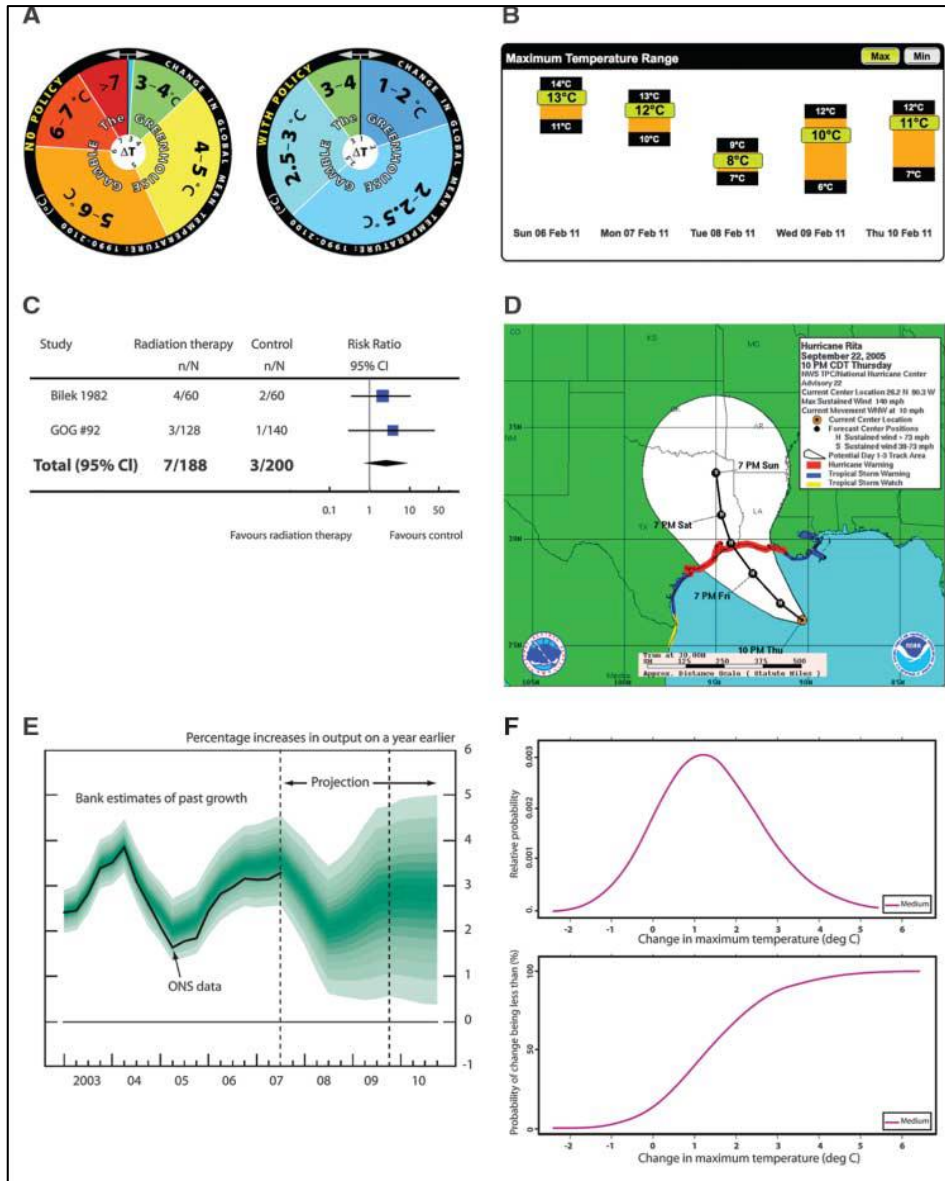


FIGURE 1. Two kinds of frequency trees for HIV testing: relative frequencies (left), which are nontransparent for many people, and natural frequencies (right), which are transparent.

Spiegelhalter et al. (2011): Visualizing uncertainty about the future

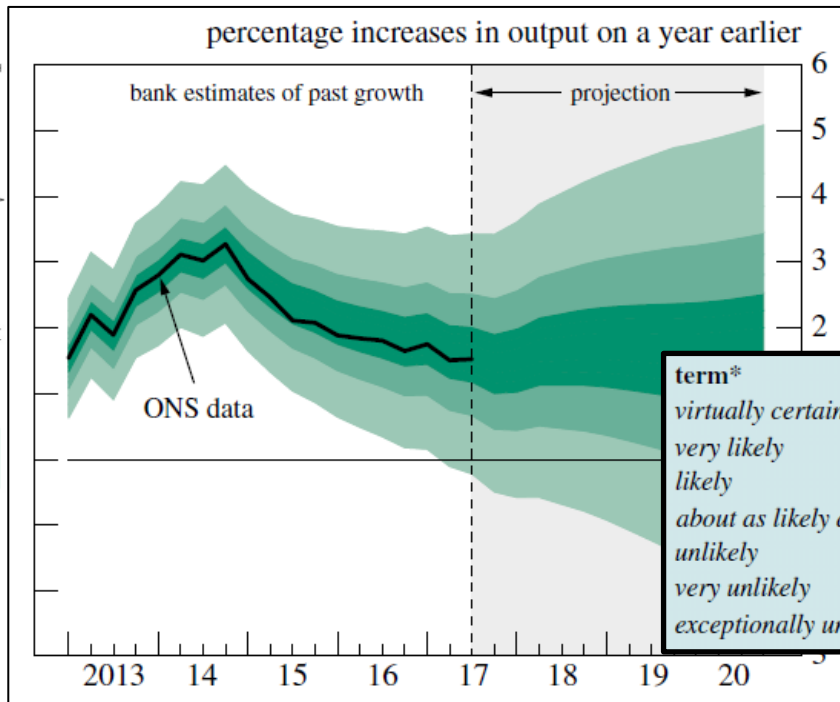
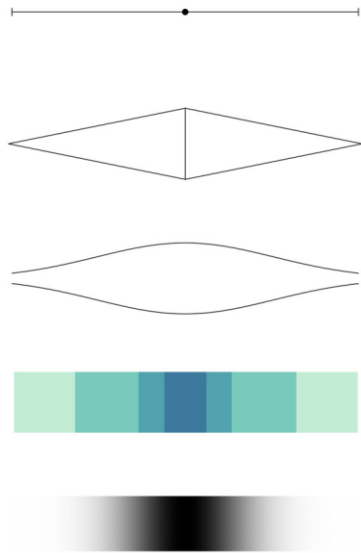
Fig. 5. Visualizations of probability distributions for continuous quantities.



**Decreasing
precision**



- i. A full explicit probability distribution
- ii. A summary of a distribution
- iii. A rounded number, range or an order-of-magnitude assessment
- iv. A predefined categorisation of uncertainty
- v. A qualifying verbal statement
- vi. A list of possibilities or scenarios
- vii. Informally mentioning the existence of uncertainty
- viii. No mention of uncertainty
- ix. Explicit denial that uncertainty exists



R. Soc. open sci. 6: 181870.

<http://dx.doi.org/10.1098/rsos.181870>

term*

virtually certain

very likely

likely

about as likely as not

unlikely

very unlikely

exceptionally unlikely

likelihood of the outcome

99–100% probability

99–100% probability

66–100% probability

33–66% probability

0–33% probability

0–10% probability

0–1% probability

Visualization in Bayesian workflow

Jonah Gabry†

Department of Statistics and ISERP, Columbia University, New York, USA.

E-mail: jonah.sol.gabry@columbia.edu

Daniel Simpson†

Department of Statistical Sciences, University of Toronto, Canada.

Aki Vehtari

Department of Computer Science, Aalto University, Espoo, Finland.

Michael Betancourt

ISERP, Columbia University, and Symplectomorphic, LLC, New York, USA.

Andrew Gelman

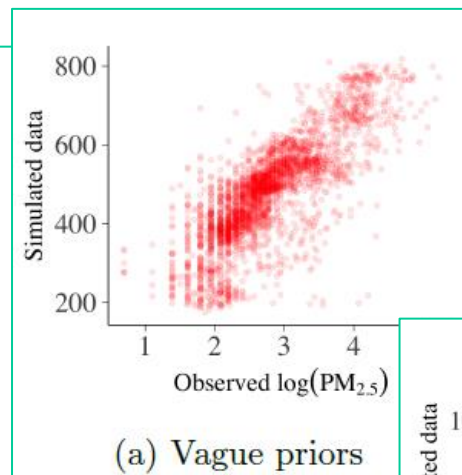
Departments of Statistics and Political Science, Columbia University, New York, USA.

Summary. Bayesian data analysis is about more than just computing a posterior distribution, and Bayesian visualization is about more than trace plots of Markov chains. Practical Bayesian data analysis, like all data analysis, is an iterative process of model building, inference, model checking and evaluation, and model expansion. Visualization is helpful in each of these stages of the Bayesian workflow and it is indispensable when drawing inferences from the types of modern, high-dimensional models that are used by applied researchers.

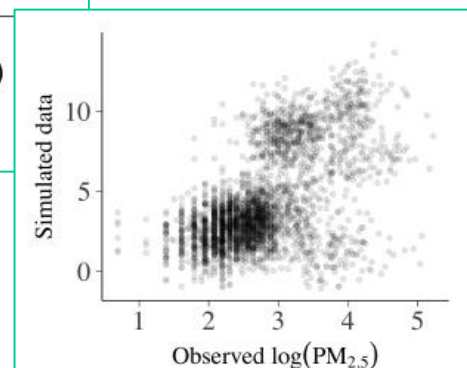
1. Introduction and running example

Visualization is a vital tool for data analysis, and its role is well established in both the exploratory and final presentation stages of a statistical workflow. In this paper, we argue that the same visualization tools should be used at all points during an analysis. We illustrate this thesis by following a single real example, estimating the global concentration of a certain type of air pollution, through all of the phases of statistical workflow: (a) Exploratory data analysis to aid in setting up an initial model; (b) Computational model checks using fake-data simulation and the prior predictive distribution; (c) Computational checks to ensure the inference algorithm works reliably, (d) Posterior predictive checks and other juxtapositions of data and predictions under the fitted model; (e) Model comparison via tools such as cross-validation.

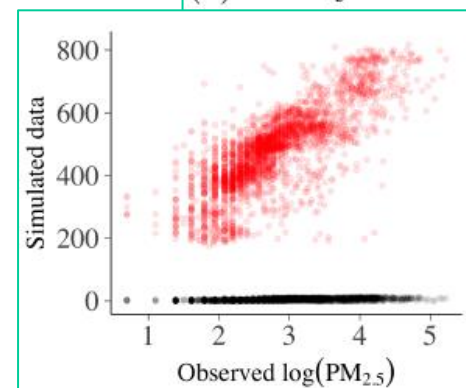
The tools developed in this paper are implemented in the `bayesplot` R package (Gabry, 2017; R Core Team, 2017), which uses `ggplot2` (Wickham, 2009) and is linked



(a) Vague priors

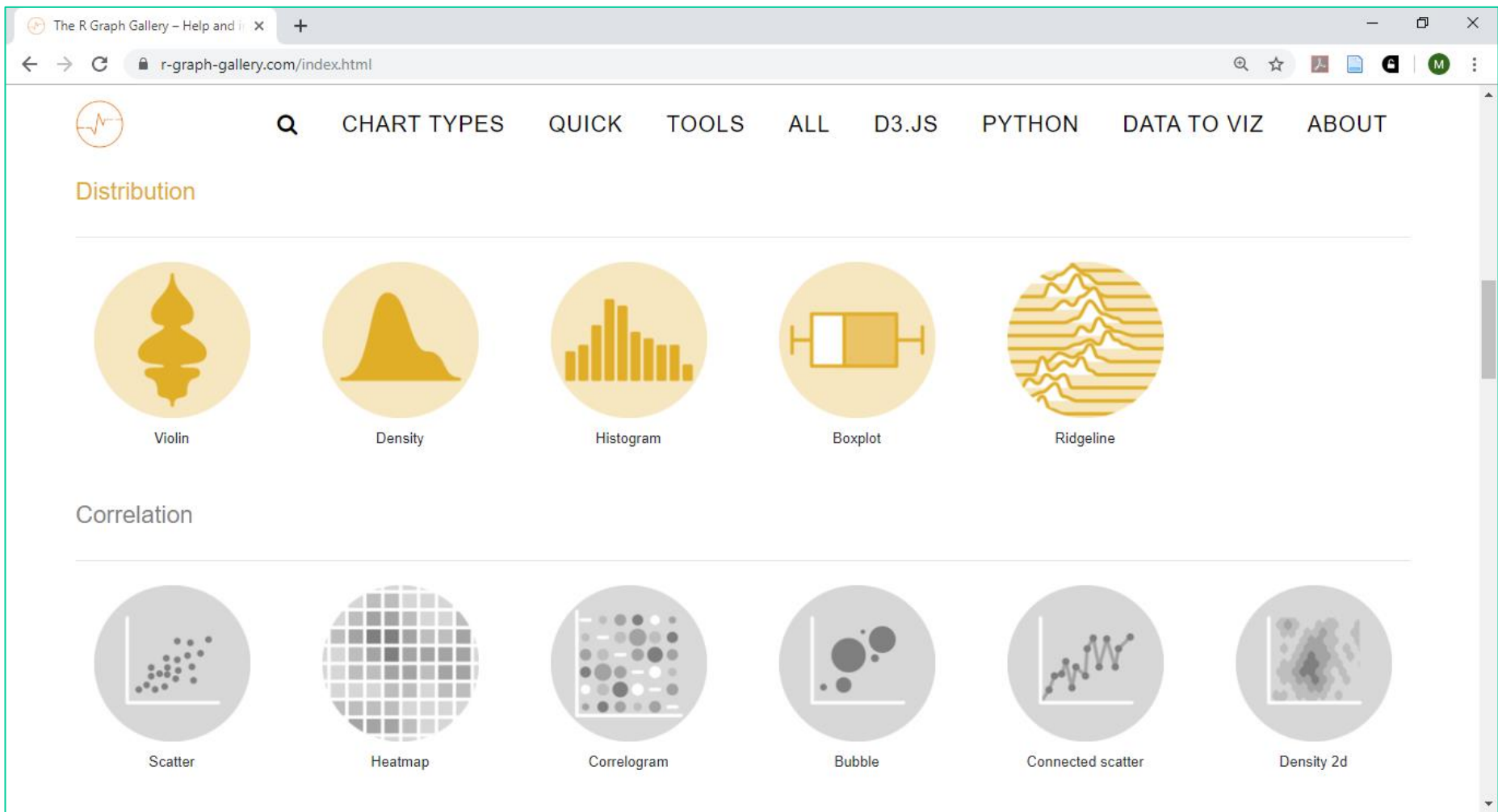


(b) Weakly informative priors



(c) Comparison

The R Graph Gallery: <https://www.r-graph-gallery.com/>



The R Graph Gallery - Help and i X +

r-graph-gallery.com/index.html

CHART TYPES QUICK TOOLS ALL D3.JS PYTHON DATA TO VIZ ABOUT

Distribution

- Violin
- Density
- Histogram
- Boxplot
- Ridgeline

Correlation

- Scatter
- Heatmap
- Correlogram
- Bubble
- Connected scatter
- Density 2d

4. Visualisation of uncertainty: Examples CEH

3.11 Parameter correlations

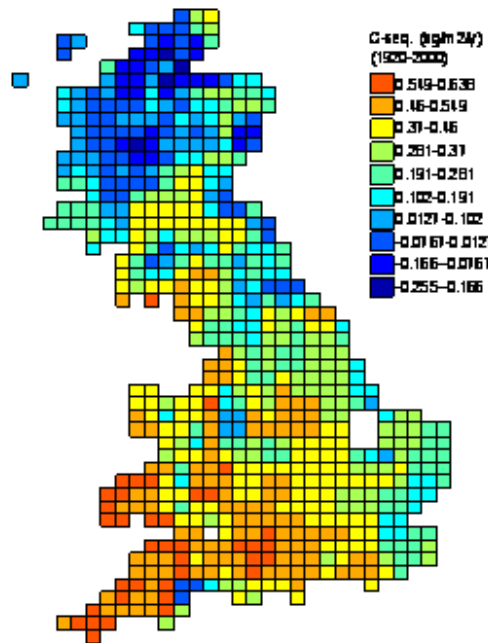
39 parameters

39 parameters

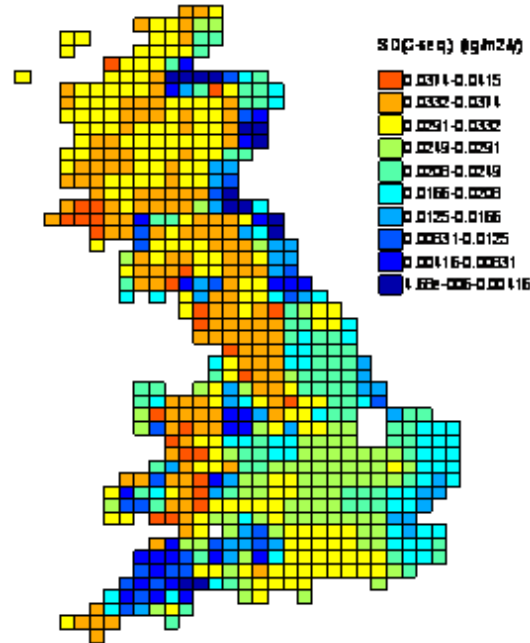
	CL0	CR0	CW0	BETA	CO20	FLMAX	FW	GAMMA	KCA	KCAEXP	KDL	KDR	KDW	KH	KHEXP	KLAIMAX	KNMIN	KNUPT	KTA	KTB	KTREE	LUE0	NLCONMIN	NLCONMAX	NRCON	NWCON	SLA	CLITTO	CSOMF0	CSOMS0	NLITTO	NSOMF0	NSOMS0
CL0	1.00	0.60	-0.67	-0.58	0.25	-0.16	0.51	0.46	0.26	0.12	0.64	0.59	0.38	-0.42	-0.07	0.71	-0.28	0.17	-0.64	-0.32	-0.58	0.23	0.55	0.52	0.12	0.50	-0.58	0.10	0.50	-0.66	-0.57	0.55	0.62
CR0	0.60	1.00	-0.49	-0.54	0.17	0.40	0.01	0.24	0.51	0.56	0.49	0.96	-0.19	-0.09	0.06	0.55	0.07	0.83	-0.60	-0.81	-0.21	-0.17	0.61	0.67	0.20	0.65	-0.54	-0.05	0.33	-0.29	0.05	0.46	0.61
CW0	-0.67	-0.49	1.00	0.91	0.24	0.45	-0.70	-0.82	-0.23	0.03	-0.74	-0.57	-0.74	0.77	-0.31	-0.98	0.76	-0.10	0.85	0.14	0.78	-0.61	-0.84	-0.91	0.51	-0.81	0.77	-0.30	-0.38	0.84	0.33	-0.88	-0.90
BETA	-0.58	-0.54	0.91	1.00	0.30	0.42	-0.78	-0.79	-0.46	-0.08	-0.79	-0.61	-0.66	0.81	0.04	-0.95	0.60	-0.32	0.94	0.17	0.61	-0.59	-0.98	-0.95	0.29	-0.94	0.84	0.01	-0.46	0.83	-0.01	-0.94	-0.96
CO20	0.25	0.17	0.24	0.30	1.00	0.05	-0.26	-0.41	-0.33	-0.28	0.11	0.09	-0.35	0.67	-0.02	-0.21	0.62	0.00	0.37	0.06	-0.22	-0.76	-0.33	-0.37	0.15	-0.19	0.57	-0.33	-0.34	-0.02	-0.28	-0.54	-0.36
FLMAX	-0.16	0.40	0.45	0.42	0.05	1.00	-0.69	-0.62	0.43	0.82	-0.56	0.25	-0.87	0.54	-0.05	-0.40	0.59	0.64	0.19	-0.81	0.74	-0.49	-0.31	-0.18	0.61	-0.33	0.06	-0.14	0.21	0.75	0.36	-0.35	-0.21
FW	0.51	0.01	-0.70	-0.78	-0.26	-0.69	1.00	0.61	0.32	-0.18	0.56	0.05	0.86	-0.83	-0.28	0.77	-0.60	-0.16	-0.75	0.26	-0.55	0.76	0.68	0.58	-0.25	0.58	-0.63	-0.17	0.54	-0.77	-0.13	0.72	0.72
GAMMA	0.46	0.24	-0.82	-0.79	-0.41	-0.62	0.61	1.00	-0.05	-0.28	0.82	0.45	0.78	-0.82	0.19	0.75	-0.81	-0.06	-0.64	0.14	-0.72	0.63	0.80	0.73	-0.46	0.78	-0.65	0.49	0.06	0.83	-0.31	0.87	0.67
KCA	0.26	0.51	-0.23	-0.46	-0.33	0.43	0.32	-0.05	1.00	0.84	-0.01	0.38	-0.10	-0.34	-0.49	0.39	0.07	0.72	-0.68	-0.69	0.35	0.30	0.49	0.51	0.47	0.37	-0.69	-0.49	0.86	0.05	0.54	0.45	0.62
KCAEXP	0.12	0.56	0.03	-0.08	-0.28	0.82	-0.18	-0.28	0.84	1.00	-0.30	0.41	-0.48	0.00	-0.24	0.07	0.24	0.76	-0.36	-0.91	0.59	0.01	0.16	0.27	0.59	0.06	-0.48	-0.22	0.68	0.42	0.44	0.16	0.32
KDL	0.64	0.49	-0.74	-0.79	0.11	-0.56	0.56	0.82	-0.01	-0.30	1.00	0.64	0.56	-0.53	-0.03	0.73	-0.39	0.17	-0.61	0.07	-0.81	0.21	0.81	0.67	-0.25	0.88	-0.48	0.10	-0.02	-0.93	-0.25	0.70	0.63
KDR	0.59	0.96	-0.57	-0.61	0.09	0.25	0.05	0.45	0.38	0.41	0.64	1.00	-0.06	-0.20	0.12	0.59	-0.07	0.75	-0.61	-0.69	-0.34	-0.10	0.70	0.72	0.09	0.75	-0.57	0.10	0.19	-0.42	-0.01	0.57	0.63
KDW	0.38	-0.19	-0.74	-0.66	-0.35	-0.87	0.86	0.78	-0.10	-0.48	0.56	-0.06	1.00	-0.84	0.12	0.70	-0.86	-0.49	-0.54	0.49	-0.73	0.81	0.54	0.50	-0.60	0.47	-0.48	0.29	0.21	-0.81	-0.41	0.67	0.56
KH	-0.42	-0.09	0.77	0.81	0.67	0.54	-0.83	-0.82	-0.34	0.00	-0.53	-0.20	-0.84	1.00	0.07	-0.78	0.85	0.08	0.80	-0.07	0.44	-0.93	-0.77	-0.73	0.30	-0.64	0.84	-0.25	-0.52	0.68	0.12	-0.92	-0.79
KHEXP	-0.07	0.06	-0.31	0.04	-0.02	-0.05	-0.28	0.19	-0.49	-0.24	-0.03	0.12	0.12	0.07	1.00	0.14	-0.43	0.26	0.14	0.00	-0.40	-0.01	-0.12	0.15	-0.76	-0.05	0.12	0.72	-0.37	-0.05	-0.47	-0.02	0.00
KLAIMAX	0.71	0.55	-0.98	-0.95	-0.21	-0.40	0.77	0.75	0.39	0.07	0.73	0.59	0.70	-0.78	0.14	1.00	-0.67	0.21	-0.93	-0.21	-0.70	0.60	0.88	0.93	-0.38	0.83	-0.82	0.11	0.51	-0.83	-0.22	0.89	0.96
KNMIN	-0.28	0.07	0.76	0.60	0.62	0.59	-0.60	-0.81	0.07	0.24	-0.39	-0.07	-0.86	0.85	-0.43	-0.67	1.00	0.38	0.53	-0.22	0.58	-0.86	-0.52	-0.59	0.66	-0.42	0.60	-0.63	-0.22	0.61	0.42	-0.73	-0.58
KNUPT	0.17	0.83	-0.10	-0.32	0.00	0.64	-0.16	-0.06	0.72	0.76	0.17	0.75	-0.49	0.08	-0.26	0.21	0.38	1.00	-0.43	-0.83	0.28	-0.27	0.45	0.46	0.47	0.48	-0.41	-0.38	0.33	0.10	0.58	0.26	0.41
KTA	-0.64	-0.60	0.85	0.94	0.37	0.19	-0.75	-0.64	-0.68	-0.36	-0.61	-0.61	-0.54	0.80	0.14	-0.93	0.53	-0.43	1.00	0.39	0.40	-0.64	-0.92	-0.93	0.08	-0.83	0.94	0.07	-0.71	0.66	-0.05	-0.92	-0.99
KTB	-0.32	-0.81	0.14	0.17	0.06	-0.81	0.26	0.14	-0.69	-0.91	0.07	-0.69	0.49	-0.07	0.00	-0.21	-0.22	-0.83	0.39	1.00	-0.33	0.16	-0.25	-0.39	-0.46	-0.21	0.47	0.05	-0.52	-0.25	-0.22	-0.21	-0.38
KTREE	-0.58	-0.21	0.78	0.61	-0.22	0.74	-0.55	-0.72	0.35	0.59	-0.81	-0.34	-0.73	0.44	-0.40	-0.70	0.58	0.28	0.40	-0.33	1.00	-0.26	-0.52	-0.51	0.66	-0.58	0.24	-0.32	0.15	0.91	0.60	-0.50	-0.48
LUE0	0.23	-0.17	-0.61	-0.59	-0.76	-0.49	0.76	0.63	0.30	0.01	0.21	-0.10	0.81	-0.93	-0.01	0.60	-0.86	-0.27	-0.64	0.16	-0.26	1.00	0.52	0.53	-0.33	0.35	0.72	0.28	0.56	-0.45	-0.13	0.73	0.62
NLCONMIN	0.55	0.61	-0.84	-0.98	-0.33	-0.31	0.68	0.80	0.49	0.16	0.81	0.70	0.54	-0.77	-0.12	0.88	-0.52	0.45	-0.92	-0.25	-0.52	1.00	0.94	-0.16	0.97	-0.85	0.00	0.41	-0.77	0.10	0.95	0.92	
NLCONMAX	0.52	0.67	-0.91	-0.95	-0.37	-0.18	0.58	0.73	0.51	0.27	0.67	0.72	0.50	-0.73	0.15	0.93	-0.59	0.46	-0.93	-0.39	-0.51	0.53	0.94	1.00	-0.32	0.91	-0.87	0.11	0.46	-0.67	0.05	0.92	0.96
NRCON	0.12	0.20	0.51	0.29	0.15	0.61	-0.25	-0.46	0.47	0.59	-0.25	0.09	-0.60	0.30	-0.76	-0.38	0.66	0.47	0.08	-0.46	0.66	-0.33	-0.16	-0.32	1.00	-0.22	-0.01	-0.46	0.34	0.44	0.31	-0.23	-0.21
NWCON	0.50	0.65	-0.81	-0.94	-0.19	-0.33	0.58	0.78	0.37	0.06	0.88	0.75	0.47	-0.64	-0.05	0.83	-0.42	0.48	-0.83	-0.21	-0.58	0.35	0.97	0.91	-0.22	1.00	-0.72	-0.03	0.23	0.79	0.12	0.86	0.85
SLA	-0.58	-0.54	0.77	0.84	0.57	0.06	-0.63	-0.65	-0.69	-0.48	-0.48	-0.57	-0.48	0.84	0.12	-0.82	0.60	0.41	0.94	0.47	0.24	-0.72	-0.85	-0.87	-0.01	-0.72	1.00	-0.13	-0.75	-0.51	-0.03	-0.93	-0.92
CLITTO	0.10	-0.05	-0.30	0.01	-0.33	-0.14	-0.17	0.49	-0.49	-0.22	0.10	0.10	0.29	-0.25	0.72	0.11	-0.63	-0.38	0.07	0.05	-0.32	0.28	0.00	0.11	-0.46	-0.03	-0.13	1.00	-0.25	-0.15	-0.64	0.22	0.00
CSOMF0	0.50	0.33	-0.38	-0.46	-0.34	0.21	0.54	0.06	0.86	0.68	-0.02	0.19	0.21	-0.52	-0.37	0.51	-0.22	0.33	-0.71	-0.52	0.15	0.56	0.41	0.46	0.34	0.23	0.75	-0.25	1.00	-0.10	0.09	0.50	0.65
CSOMS0	-0.66	-0.29	0.84	0.83	-0.02	0.75	-0.77	-0.85	0.05	0.42	-0.93	-0.42	-0.81	0.68	-0.05	-0.83	0.61	0.10	0.66	-0.25	0.91	-0.45	-0.77	-0.67	0.44	-0.79	-0.51	-0.15	-0.10	1.00	0.39	-0.74	-0.68
NLITTO	-0.57	0.05	0.33	-0.01	-0.28	0.36	-0.13	-0.31	0.54	0.44	-0.25	-0.01	-0.41	0.12	-0.47	-0.22	0.42	0.58	-0.05	-0.22	0.60	-0.13	0.10	0.05	0.31	0.12	-0.03	-0.64	0.09	0.39	1.00	-0.05	0.01
NSOMF0	0.55	0.46	-0.88	-0.94	-0.54	-0.35	0.72	0.87	0.45	0.16	0.70	0.57	0.67	-0.92	-0.02	0.89	-0.73	0.26	-0.92	-0.21	-0.50	0.73	0.95	0.92	-0.23	0.86	-0.93	0.22	0.50	-0.74	-0.05	1.00	0.92
NSOMS0	0.62	0.61	-0.90	-0.96	-0.36	-0.21	0.72	0.67	0.62	0.32	0.63	0.63	0.56	-0.79	0.00	0.96	-0.58	0.41	-0.99	-0.38	-0.48	0.62	0.92	0.96	-0.21	0.85	-0.92	0.00	0.65	-0.68	0.01	0.92	1.00
NSMINO	-0.16	-0.31	-0.47	-0.41	-0.64	-0.43	0.56	0.33	0.16	-0.09	-0.06	-0.30	0.66	-0.63	0.29	0.45	-0.72	-0.33	-0.40	0.25	-0.21	0.79	0.27	0.41	-0.66	0.16	-0.39	0.14	0.33	-0.23	0.06	0.42	0.45
FLITTSOMF	0.48	0.60	-0.01	0.08	0.61	0.31	-0.43	0.03	-0.22	0.05	0.36	0.63	-0.39	0.40	0.15	-0.02	0.34	0.33	0.12														

3.11 Maps of (1) predictions, (2) uncertainties

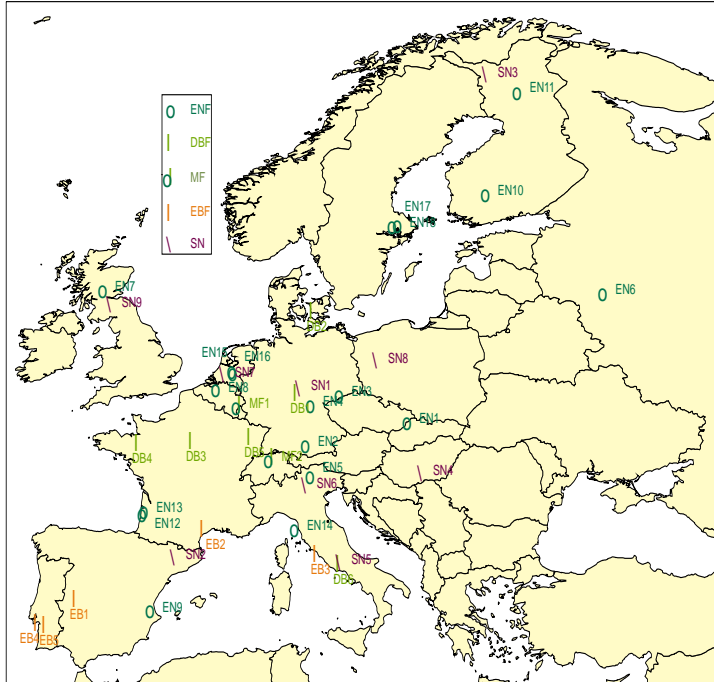
C-sequestration
(model output for
1920-2000)



Uncertainty of
C-sequestration

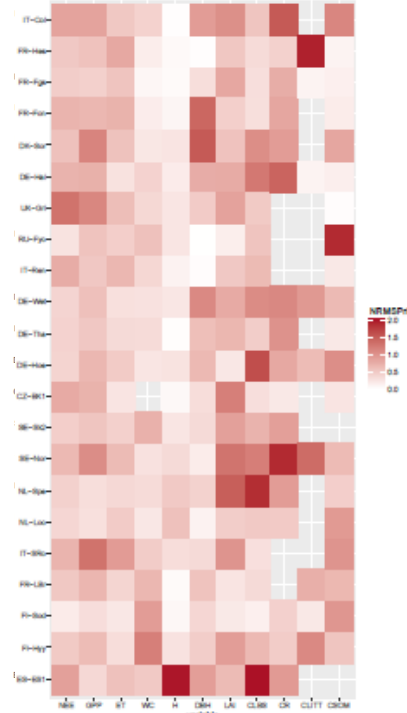


4.1 Site-specific vs. generic BC for European forest

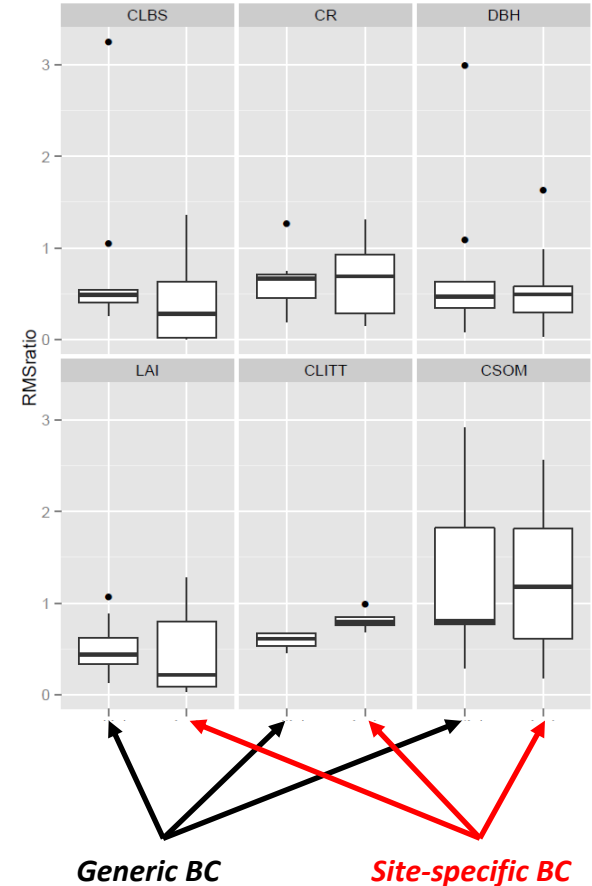


Geographical distribution of NitroEurope nitrogen deposition monitoring sites. ENF: evergreen needle leaf forest; DBF: deciduous broadleaf forest

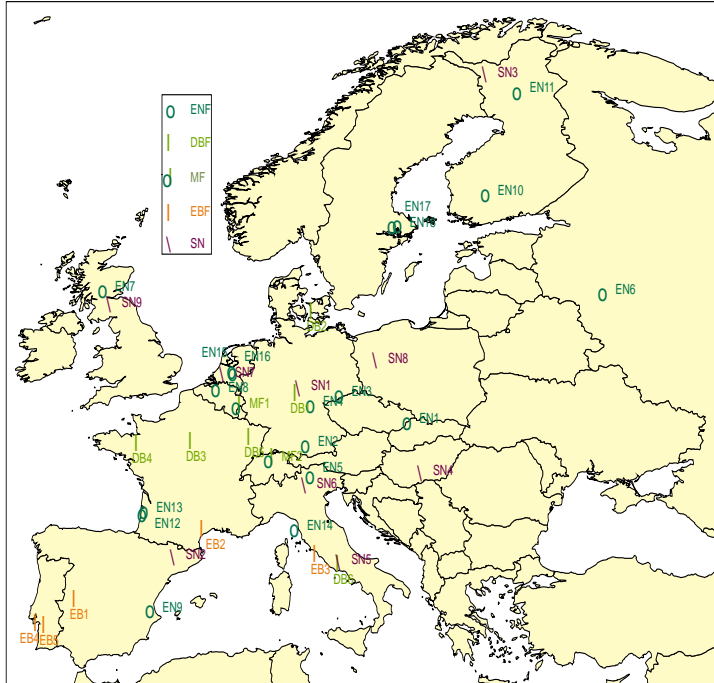
RMS - ratio



RMS - ratio

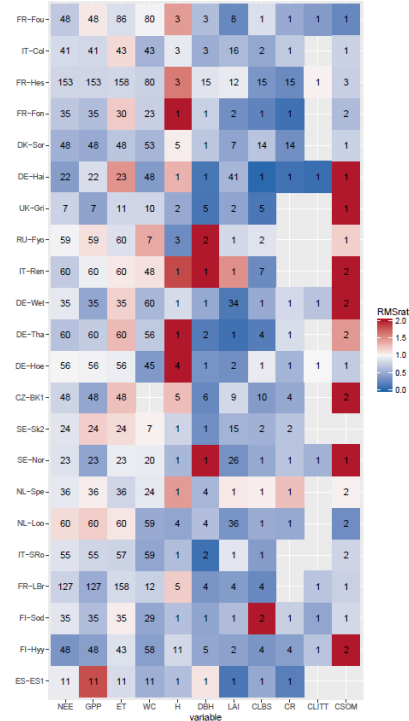


4.1 Site-specific vs. generic BC for European forest

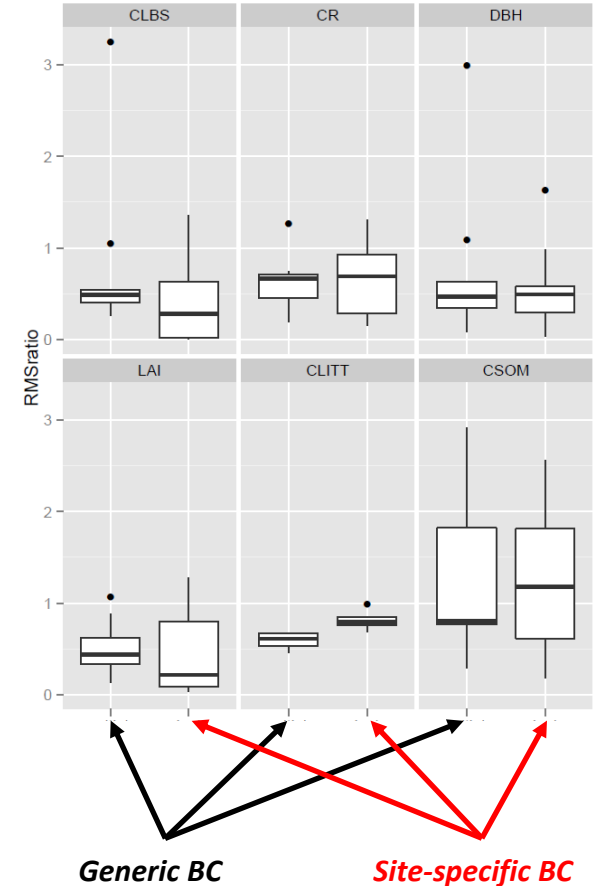


Geographical distribution of NitroEurope nitrogen deposition monitoring sites. ENF: evergreen needle leaf forest; DBF: deciduous broadleaf forest

RMS - ratio

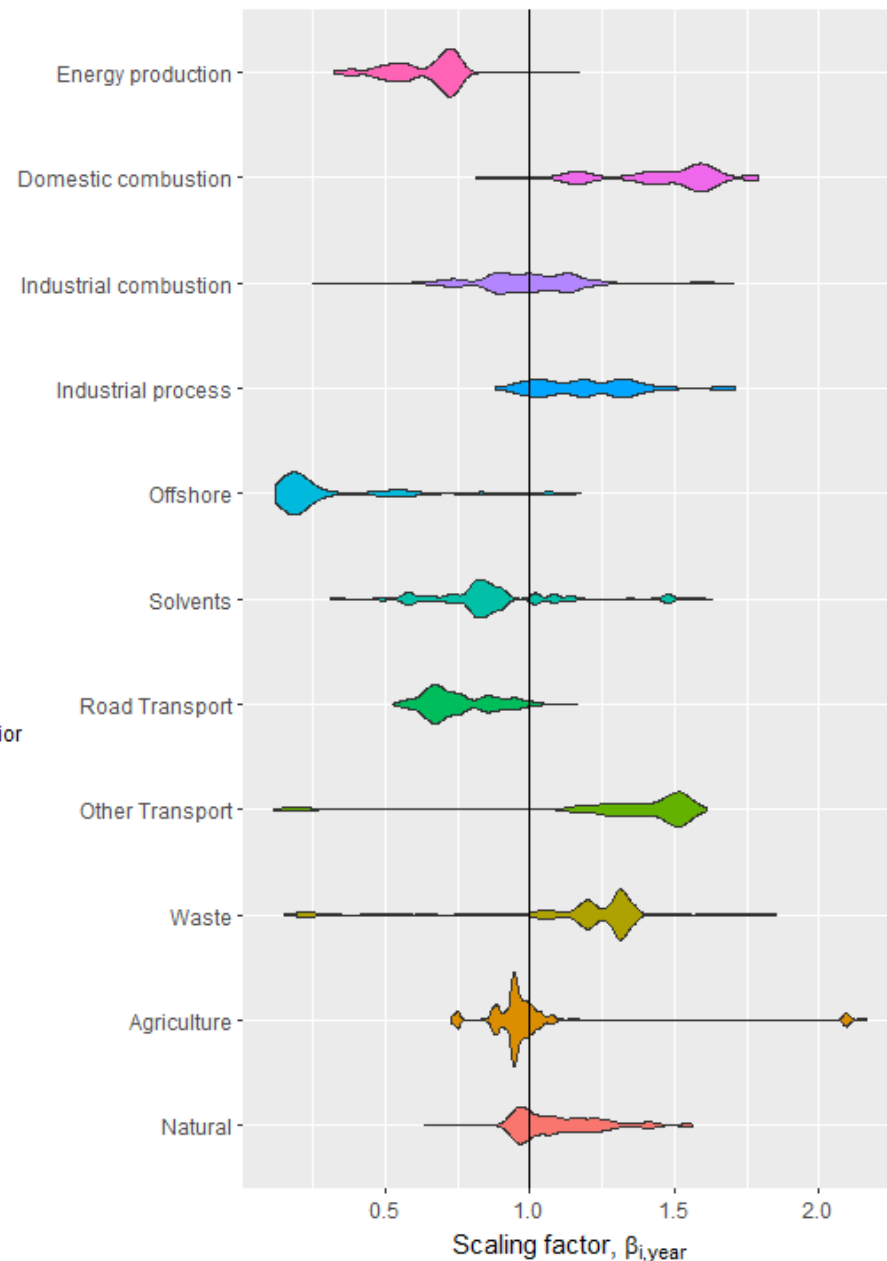
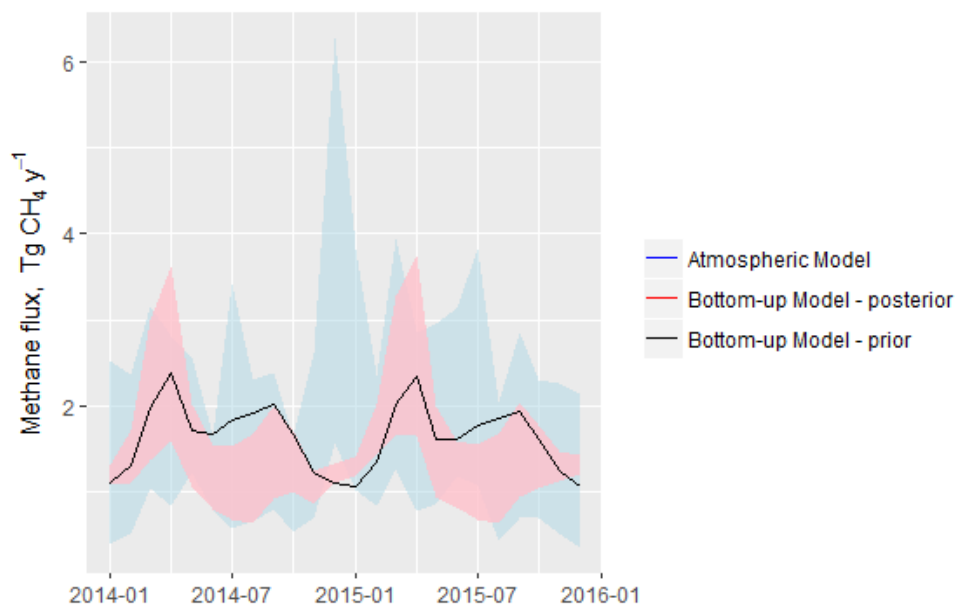


RMS - ratio



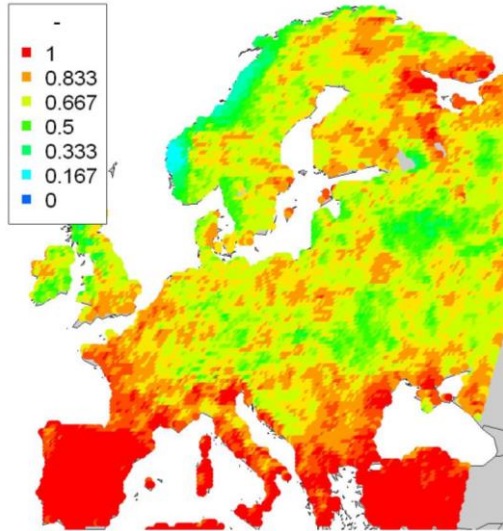
4.2 Reconciling LUC-inventory models with atmospheric inversion

- Each emission sector has a characteristic spatial & temporal pattern
- Use this in a Bayesian analysis of the parameters of a “bottom-up” model (anthropogenic & biogenic)
- Derive sector-wise scaling factors = multipliers needed to match atmospheric model
- Posterior distribution for methane shown (2014-2015)

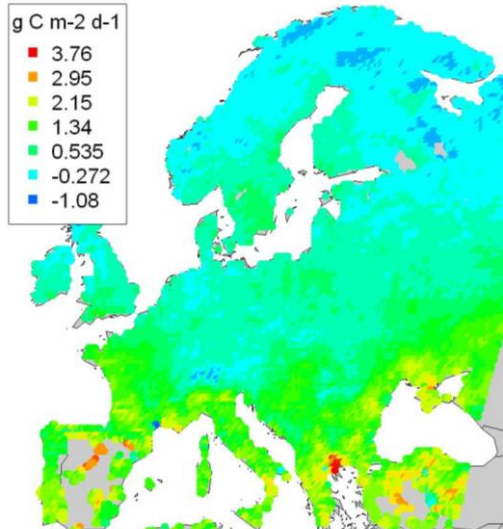


4.5 Drought-risk analysis for NPP in 2071-2100

Probability of drought (PH)

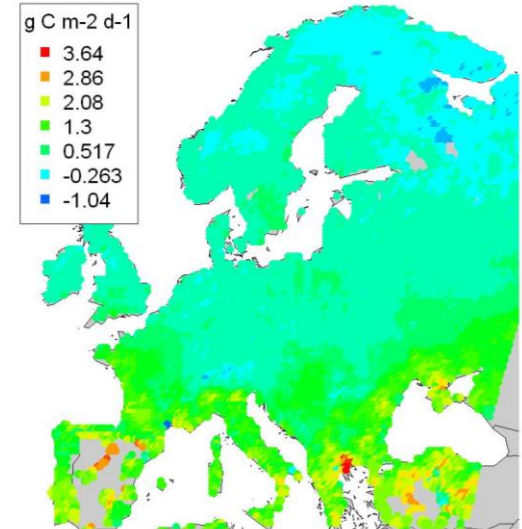


Vulnerability (V)



$$R = P(H) V$$

Risk (R)
= expectation of loss

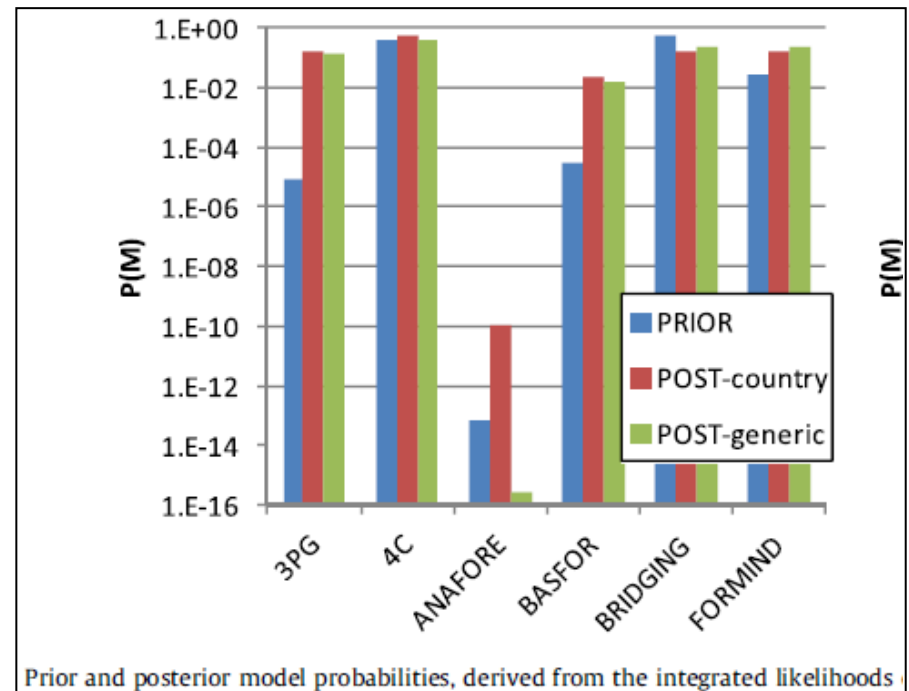
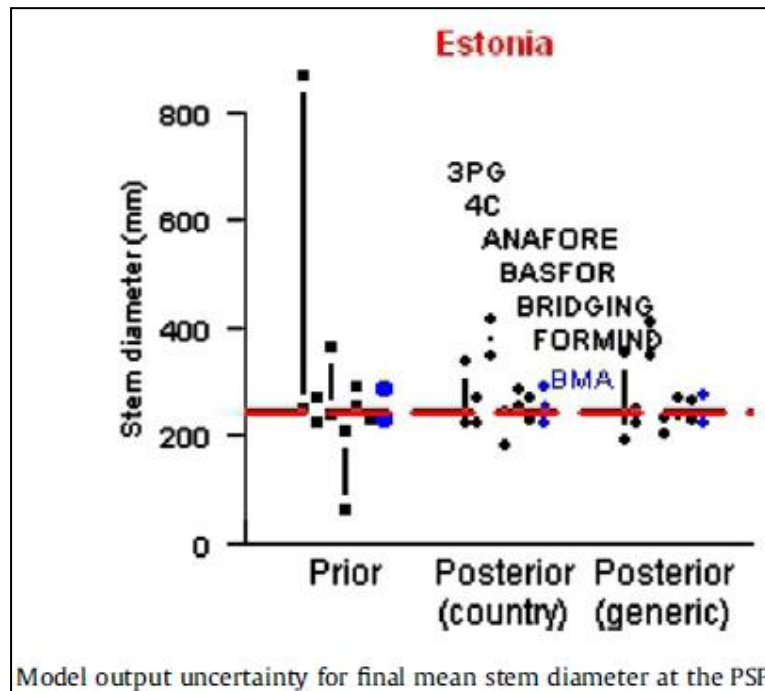


3.8 Bayesian calibration, comparison and averaging of six forest models, using data from Scots pine stands across Europe

Forest Ecology and Management 289 (2013) 255–268

Bayesian calibration, comparison and averaging of six forest models, using data from Scots pine stands across Europe

M. van Oijen^{a,*}, C. Reyer^b, F.J. Bohn^c, D.R. Cameron^a, G. Deckmyn^d, M. Flechsig^b, S. Härkönen^e, F. Hartig^c, A. Huth^c, A. Kiviste^f, P. Lasch^b, A. Mäkelä^g, T. Mette^h, F. Minunnoⁱ, W. Rammer^j



INTERMEZZO

Shiny app for BELUC

Shiny [app](#) for MU-MAP